







ROBOTICS TECHNICIAN



LEARNER GUIDE National Vocational Certificate Level 1-4

Version 1 - October, 2019





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LEARNER GUIDE

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- Learning Units:
 - Learning Units are the main sections within each module
- Learning outcomes:
 - o Learning outcomes of each learning units are taken from the curriculum document
- Learning Elements:
 - This is the main content of your learner's guide with detail of the knowledge and skills (practical activities, projects, assignments, practices etc.) you will require to achieve learning outcomes stated in the curriculum
 - o This section will include examples, photographs and illustrations relating to each learning outcome
- Summary of modules:
 - o This contains the summary of the modules that make up your learner's guide
- Frequently asked questions:
 - These have been added to provide further explanation and clarity on some of the difficult concepts and areas. This further helps you in preparing for your assessment.
- Multiple choice questions for self-test:
 - These are provided as an exercise at the end of your learner's guide to help you in preparing for your assessment.

Modules

Module: 0714001050 Perform basic machining operations

Objective of the Module: This competency standard is designed to gain basic knowledge and skills required to read and interpret assembly drawings, perform bench work operations using different tools and equipment, perform lathe machine operations and prepare materials for a welding job in accordance with the organization's approved guidelines and procedures.

Duration:	Total hours	50 Hrs	Theory:	10 Hrs	Practical	40 Hrs
Learning Unit	Learnir	ig Outcomes	Learning E	lements		Materials
						(Tools &
						Equipment)
						Required
LU1: Interpret Assembly	The trainee mu	st be able to:	Demonstrate the	lines on physical drav	wing sheets	• Samplo drawing
Drawings	Recognize ba	sics of lines used ir	edescribe types of	lines use in engineer	ring drawings	
	engineering d	rawings	 describe the lines 	thickness qualities	-	sneets of Sketches
			• demonstrate per	ncil types to draw	the engineering	

	• Understand different types of lines	drawing lines	 Layout tools
	in engineering drawingsUnderstand types of drawing views	 develop the insight to see the different views of an engineering parts demonstrate the engineering views on actual drawing sheets 	Measuring devices (screw gauge, Vernier calliper)
	 Identify assembly requirements according to drawings 	 demonstrate the assembly points mention in an industrial drawing demonstrate the signs using in assembly drawings demonstrate the assembly drawing sheet and its building on any commercial software Praticle-1 Draw the free hand sketches of assembly parts on sketch books draw the different assembly lines on drawing sheet draw the free hand sketches of drawing views explain the drawing sheets using in real time industrial assembly lines 	 Handheld calculator Hacksaw Special robot tool kit P.P.E Drill set Drill machine Grinder Hacksaw
LU2: Perform Bench Work on Metallic Surfaces	 The trainee must be able to: Carry-Out Sawing File the Work-Piece Carry out Drilling Process Produce Threads on Work-Piece Perform Hand Reaming 	 Describe the types of foils and their usage describe the using of bench voices Describe the threads types demonstrate the types of tap die for making threads on work piece Describe the drilling & reaming process Demonstrate the drilling & reaming tools on industrial grounds Practicle-1 make the work piece using foils and tap dies using bench voices perform the drilling operations on work piece using bench voices develop the work piece/die using the reaming tools 	 Drill set Drill machine Grinder Turret lathe machine Tool grinder Lathe cutting tools Multi- process welding equipment

			Т		
LU3. Prepare Lathe Machine	The trainee must be able to:	Describe the lathe machine parts Describe the lathe machine operations	•	Base metal	S
	Prepare Materials for Lathe	Demonstrate the lathe machine tools used for different	•	Welding ma	achine
	Operations	operations	•	Engine	lathe
	 Select Tools and Equipment 			machine	
	Set Lathe Machine for		•	Personal sa	afety kits
	Operations		•	Hardware	complete
				tool kit	
		Practicle-1			
		 develop the different work pieces using lathe machine operations 			
		 develop the machine parts used in an assembly line 			
LU4. Prepare Materials for Welding	The trainee must be able to:	 Describe the welding and its types Demonstrate the welding processes 			
holding	Select and Mark Material/s as per	describe the welding rods and their usage conditions			
	Drawing/Job Requirement	describe the codes written on welding rods and their auitability with different welding conditions			
	Cut and Prepare Edge/s of Base	demonstrate the welded joints			
	Materials	• describe the needs of particular type of welding in a			
	Knowledge of welding equipment	specified condition			
	Fit-up Base Materials				
	Knowledge of materials				
		Practice-1			
		• Perform the welding operations to join the real time			
		industrial broken parts used in an assembly line/robotic			

production line.	
Practice-2	
Select, arrange and prepare tools and equipment for	
ARC welding.	
Select, arrange and prepare tools and equipment for	
GAS welding.	

Module 1:



"	Lathe Machine Operation
	https://www.youtube.com/watch?v=XXpOwsD0fWM
Contraction of the second seco	
▶ ▶ ♠ ♠) 3:01/10:08 🗰 🗖	
	Pohot CNC Machining
	Robot CINC Machining
	https://youtu.be/3o1waj2fxgY
	https://youtu.be/oJPGioHgNjU
GIZELIS	
I ROBOTICS	
Robotic CNC	
Machining	
▶ ▶ ♦ • 0:07/10:22	



Module: 0714001051 Operate the electronic measuring instruments

Objective of the Module:

The purpose of this competency standard is to become familiar with different types of electrical and electronic measuring instruments. After completion of this competency standard the candidate will be skilled in taking measurement from different types of electrical and electronic measuring instruments.

Duration:	Total hours	50	Theor	20	Practical	30
			V:			

Learning Unit	Learning Outcomes	Learning Elements	Materials (Tools & Equipment) Required
LU1. Evaluate the measuring instrument	 The trainee must be able to: Classify the instrument type (analogue/digital). Check the type of power source needed. Evaluate and assemble the device and probes with proper procedure (as per manual). Perform zero error tests as described in the procedure. Identify the measuring units/parameters of the device as per SOP. Set the readability of the instrument with respect to range. Record the findings and develop the report. 	 Demonstrate evaluation procedure Explain Basic instruments and its types. Explain and demonstrate Analog instruments. Explain and demonstrate Digital instruments. Explain and demonstrate operation of analogue measuring instruments AC and DC instruments Direct method mearing instruments Comparison method mearing instruments Indicating instruments Electromechanical instruments Integrating instruments Explain and demonstrate operation of digital measuring instruments Explain and demonstrate operation of digital measuring instruments Explain and demonstrate DC power sources Explain and demonstrate Ac power Sources understanding of manual and diagrams for assembling the device. explain zero error perform zero error test on device. basic measuring parameter with their units (voltage 	 Electrical test bench Multi-meter Test probes Hand glove Analogy meter DMM Thermometer 2-channel AC/DC Power supply 5V, 12V, 24V Oscilloscope Breadboard trainer Power source (AC/DC) Digital multi meter Lux meter Power meter Power factor

		 current resistance capacitance inductance and frequency) operation of multi range meter. selection of range with respect to desired parameter. procedure for recording as per manual of equipment procedure for reporting Practical: Perform Zero error test.	 meter, Frequency meter Energy meter etc. Electrical test bench Digital Multi- meter Digital Power source (AC/DC)
LU2.Operate Analogue instruments	 The trainee must be able to: Determine the type of electrical/electronic parameter to be measures. Select the relevant measuring instrument as per parameter to be measured. Test point identification for measurement. Connect the instrument according to the prescribed method. Follow the procedure for reading value on the display 	 Explain overview of measuring parameter Explain selection procedure of measuring parameter Explain selection procedure of measuring instrument Explain procedure for identification of test point Explain and demonstrate selection of test point Explain methods of measurement (i.e. voltage current). Demonstrate connection procedure for measurement Demonstrate procedure to extract value according to the selected range. Demonstrate tools required for measurement Practical-1: Find resistance of standard resistor (AH-50w-1k) through analogue multi meter. Practical-2: Generate 10volt using variable power supply and then measure it using analogue multi meter 	 Manual tools Screw drivers Tweezers Tool Wire Cutter Nose plier Soldering iron Sucker Electrical test bench Power source (AC/DC) Oscilloscope Function generator IC/components Gold Aluminum Housed Wire wound Resistor-AH-50W-1k

LU3.Operate digital measuring instruments	 The trainee must be able to: Identify the type of quantity to be measures. Select the relevant measuring instrument as per parameter to be measured. Test point identification for measurement. Connect the instrument according to the prescribed method. Follow the procedure for reading value on the display 	 Explain overview of measuring parameter Explain selection procedure of measuring parameter Explain and demonstrate procedure for identification of test point Demonstrate selection of test point Demonstrate methods of measurement (i.e voltage current). Demonstrate connection procedure for measurement Demonstrate procedure to extract value according to the selected range. Practical-1: Find resistance of standard resistor (AH-50w-1k) through digital multi meter. Practical-2: Generate 10volt using variable power supply and then measure it using digital multi meter 	As Unit-1
LU4. Familiarize with basics of oscilloscope and function generator	 The trainee must be able to: Identify components and control knobs of oscilloscope. Familiarize with operating panel and display control. Adjust screen resolution and calibrate screen with probes. Measure the AC/DC signal on oscilloscope using function generator. 	 Explain Basic functionality of oscilloscope and function generator. demonstrate screen, control panel and probes demonstrate working of each knob/button explain and demonstrate how to extract reading of the signal demonstrate procedure of calibration of the oscilloscope Demonstrate procedure for the adjustment of screen resolution Demonstrate procedure to generate AC signal from function generator Demonstrate procedure to generate DC signal from 	As Unit-1

 function generator Demonstrate procedure for connection (oscilloscope with function generator) Demonstrate procedure for measurement of signal using oscilloscope.
Practical-1: Generate 5v RMS 50hz signal using function generator and measure peak voltage, peak to peak voltage, RMS voltage, time period and frequency of that signal using oscilloscope

Module 2:	
	Measuring Tools
	https://www.youtube.com/watch?v=cX5DCzyjz6k





	How to use a Function Generator and Oscilloscope https://www.youtube.com/watch?v=jWDJeiH6veQ
MSC measurement solutions www.measurement-solutions.co.uk	MetrologX4 i-Robot - The first all in one Robotic Measurement Solution https://youtu.be/wsMe8HvYw https://youtu.be/vSX5fvNT3Bo

Module: 0714001052 Use measuring instruments for mechanics

Objective of the Module:

This competency standard covers the skills and knowledge required to take measurements with Steel rule, Hook rule, Folding rule, Trammels, combination set, micrometre, Vernier calliper, various gauges and different measurement instruments.

Duration:	Total hours	50 Hrs	Theory:	14 Hrs	Practical	36
						Hrs

Learning Unit	Learning Outcomes	Learning Elements	Materials (Tools & Equipment) Required
LU1.Take measurements with graduated tools	 The trainee must be able to: Take measurements using a Steel rule Take measurements using a Hook rule Take measurements using a Folding rule Take measurements with Trammels 	 Describe units of different measuring parameters. describe the measuring techniques using different measuring equipment's Describe how to develop the own measuring tools under different circumstances demonstrate the levelling of measuring rules to get the appropriate readings Practicle-1 measure the different lengths using different types of measuring rule(s) 	 Steel rule Work piece Surface plate Steps and collars Hook rule Folding rule Trammel Combination set

LU2.Take measurements with combination set	 The trainee must be able to: Take Measurement with Square head Perform levelling with square head as spirit level Measure depth with square head as depth gauge Measure height with square head as height gauge 	 Explain the types of measuring heads demonstrate the method to take the appropriate readings from different types of measuring heads Practical-1 measure the depths of industrial parts using measuring heads manufactured by industrial robot measure the heights for industrial parts manufactured by robot using measuring gauges 	 Screw thread Micro meter Vernier Calliper Height Gauge Vernier calliper Dial thickness gauge Dial indicator
LU3.Take measurements through various gauges	 The trainee must be able to: Take measurement with fixed gauge and plug gauge. Take measurement with adjustable gauge Take measurement with small hole gauge Take measurement with telescope gauge 	 Explain different types of measuring gauges used under different operating conditions illustrate the different measuring techniques using measuring gauges demonstrate how measuring gauges are used while developing the robotic based environment 	 Coordinate measuring machines ISO tables of fits and tolerance Measurement tools

		Practical-1	
		 Measure the heights of assembly line parts using 	
		measuring gauges	
LU4.Perform	The trainee must be able to:	Explain working of micro meter	Surface plate
Micro meter	 Take measurement with outside micro-meter Take measurement with inside micro meter Take measurement with depth micro meter Measure threads with 	 demonstrate the micro meter usage under real time conditions Explain types of threads measurements using micro meter. demonstrate the threads measurements using micro meter 	 Scriber Tri square Divider Round stock Fix gauge Telescope
	micro meter		·
	Take measurement with Vernier micro meter		
		 Practical-1 measure the heights of different parts using micro meter while working on lathe machine measure the necessary heights/lengths/diameters manufactured under robotic environment using micro meters 	
LU5. Measure	The trainee must be able to:	 Explain working of Vernier tools 	Surface plate
dimensions with Vernier tools	Take measurement with Vernier calliper	 demonstrate the Vernier tool usage under real time conditions describe the types of measurements using Vernier tool 	 Radius gauge Ring Gauge
	Iake measurement with height gauge		Plug Gauge
	• Take measurement with		Angle gauge
	Vernier depth gauge		 Adjustable gauge

		 Practical-1 measure the heights of different parts using Vernier tool while working on lathe machine measure the necessary heights/lengths/diameters manufactured under robotic environment using Vernier tool 	
LU6. Perform different measurements	 The trainee must be able to: Take measurement with dial calliper Take measurement with dial thickness gauge Take measurement with dial Indicator Exercise on gauge blocks Exercise on tool makers microscope 	 Describe the measurements techniques Describe the types of tolerances & allowances in measurements techniques Describe the tool maker microscope Describe and demonstrate the robotic based measurement techniques Demonstrate the measurements techniques and tools 	 Surface gauge Dial indicator Outside Micrometer Inside Micrometer Depth Micrometer Gauge blocks Tool makers microscope

Practice on Profile Projector	Practical-1 • Measure the robotic based assembled parts using dial calliper/dial thickness gauge/dial indicators/gauge	
 Practice Of Digital Instruments Measure tolerance and allowances 	calliper/dial thickness gauge/dial indicators/gauge blocks/profile projectors/digital instruments • measure the tolerances & allowances using measuring gauges for robotic based assembled parts	

Examples and illustrations







Measuring Instruments, Least Count, Parts name and Details

https://youtu.be/J7fKbrFO_y0

https://youtu.be/lou9kAFGOjk

Module: 0714001055 Identify security arrangements for robotics equipment

Objective of the Module: The objective of this standard is to ensure identification of security arrangements, assessment of gaps in the current security protocols and report security solutions for robotic equipment. After achieving this standard, the learner will be able to ensure security arrangements for operation of robotic equipment.

Duration:	Total hours		40 Theory: 13 Pract		ical	27		
Learning Unit	Learning Outcomes			Learning Elements			Mat	erials (Tools &
							Equ Req	ipment) uired
LU1. Maintain Security logs	 The trainee must be able t Keep performance in timely and relevant. Acknowledge both performance in and negatives of the relactivities. Keep the logs factuated detailed. Create a sense of contained consistency maintaining logs. 	o: records ositives ecorded al and ntinuity while	•	Describe record keeping p Define elements of reco Errors, check in, check our Describe logs, its types an Demonstrate how to maint Define positive and negati Demonstrate how to comp negative data record.	procedure. ord keeping like t terms. Id operations. tain logs ve record data. pare event based	Time, Date,	 Personal Printer Stationar Any Rolwith semanual Log book Desk Chairs 	Computers ry items botic Equipment ecurity protocol
			Practic	al: The candidate is require logs highlighting signific workplace data of one wee	d to prepare pro cant events as ek.	oper security per given		
LU2. Follow Relevant Security Protocols	 The trainee must be able t Identify relevant s protocols as per st operating procedures. Follow instructions a standard op procedures. 	o: security andard as per perating	• • • Practic	Define security protocols. Describe limitations of sec Explain all the standard op Demonstrate various secu al: Get the data from rec	eurity protocols. Derating procedure rity protocols.	es. the security		

LU3. Audit Security Protocols	 Check whether security logs are followed as per standard operating procedures Assess current security performance Identify gaps in current security protocols 	 Explain how to check security logs. Define security performance. Describe various standard solution for security breech. Describe how to evaluate performance of security protocol. Demonstrate comprehensive audit of security protocol. 	
	 Formulate and report security solutions to supervisor 	Practical: Make a report on existing security protocols of provided workplace environment which includes procedure of checking security protocols and make a comparison with standard procedure.	





	Follow Relevant Security Protocols
	https://www.youtube.com/watch?v=F3Up7iizq9I
Robots are used to perform complex and critical tasks in all the major industry sectors	Audit Security Protocols https://www.youtube.com/watch?v=BxHYtFlKruY

Module: 0714001056 Operate Robots at workplace

Objective of the Module: This module relates with basic operation of robots in industry and identifies learning required for operation of robot at workplace as per standard operating procedures provided in the user manual. Trainee will be able to perform basic operation of a robot.

Duration:		Total hours	otal hours 50		Theory: 14 Prac		octical	36	
Learning Unit		Learning (Dutcomes		Learning	Elements		Mater Equip Requ	ials (Tools & oment) ired
LU1.Perform basic/initia before operation	I test	 The trainee must be Knowledge abored given component Ensure proper components accored by Check initial powers Perform basic component test run 	be able to: but basic workin nt connectivity o cording to instructive wer indicators alibration of robot	ng of f all ions	 Describe differ their connectivi Indicate differe Explain initial c test procedure Demonstrate te Practical-1:	rent robot compo ity nt types of indicate alibrations and pro est run	onents and or e-operative	 Robotic Pla Basic election 	atform tronic Tool Kit
		• Penomitest fun			connected by look	king at respective	indicators		
LU2. Ensure Suitabilit workplace for operation	ty of	 The trainee must be Identify suitable the robot. Identify obstact operations 	e able to: work environme es that effects	nt for robot	 Explain suital environmental Describe robo Demonstrate given robot sa 	ble work enviror hazardous tic equipment safe a suitable enviro fety.	nment and ety onment for		

	 Prepare suitable work environment for the robot. Ensure safety for the robotic equipment. 	Practical-1: Prepare suitable environments for given robot ensuring robot safety	
LU3. Follow standard procedures for operating the robot	 The trainee must be able to: Know about operation manuals of robot Identify the standard operating procedure for the robot. Follow instruction as given in standard operating procedure while operating the robot Ensure proper functioning of the robot. 	 Explain robots operating manual and its standard operating procedure Demonstrate robot basic functioning according to standard operating procedure Pactical-1: Identify and Perform any basic operation of a given robot as per standard operating procedure. 	
LU4. Perform post operation test	 The trainee must be able to: Recognize appropriate post operation test for the particular robot Follow standard operating procedure 	 Describe post-operative tests Demonstrate post-operative test as per standard operating manual. 	

to perform post operation testGenerate post operation test report	Practical-1: Perform post-operative test for given robot as per Standard operating procedure and generate test report	

Example And Illustration








Module: 0714001057 Distinguish equipment/components for assembling purpose

Objective of the Module: Robot parts include a wide variety of components related to: Manipulator, End-effector, Locomotion Device, Controller, Sensors. This competency aims at distinguishing different tools and components involved in assembly of a robot at workplace and also involves prior preparation.

Duration:	Total hours	40	Theory:	10	Practical	30
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Learning Unit	Learning Outcomes	Learning Elements	Materials (Tools & Equipment) Required
LU1. Identify different components for assembly	 The trainee must be able to: List all assembly components Distinguish between different types of components based on various traits. Label components 	 Explain assembly procedure Explain basic functionality and usage of components Explain procedure for selecting components Demonstrate procedure for selecting components Explain Characteristics of robotic component Explain Procedure for labelling the component Demonstrate Procedure for labelling the component Demonstrate Procedure for selecting component 	 Mechanical tools: Hammer, Screwdrivers & Wrenches, Saw, Square, measuring tape, Vernier callipers, Files, Centre Punch, Drill Press, Hobby Tool, soldering station, wires stripper, Sharp utility knifes, Hot glue guns, Arc Welder, Electric Heat Gun, Safety Goggles.
LU2. Arrange components in order for assembly	The trainee must be able to:	 Explain procedure of selecting components as per manual 	 Robot components kit related to: Manipulator, Actuator, End effector, Locomotion Device, Controller, Sensors

	 Know about components from user manual Identify order of assembly Recognize required components Arrange components according to identified order 	 Demonstrate procedure of selecting components as per manual Explain procedure to extract key points for assembly. Demonstrate procedure to extract key points for assembly. Explain recognition procedure Explain procedure for identifying order of assembly Demonstrate procedure for identifying order of assembly Demonstrate procedure for arranging components Demonstrate procedure for arranging components 	
LU3. Identify tools/ equipment for assembly	The trainee must be able to:List different types of toolsSelect appropriate tools for assembly	 Explain basic functionality and usage of tools/equipment Explain procedure for selecting tools/equipment Demonstrate procedure for selecting tools/equipment Practical: select all the tools for assembly as per task and differentiate mechanical & electrical components. 	As Unit-1

LU4. Arrange tools/equipment for assembly	The trainee must be able to: •Arrange tools according to identified order	 Explain procedure for arranging tools as per assembly Demonstrate procedure for arranging tools as per assembly Practical: Arrange all the tools for assembly as per given task 	As Unit-1
LU5. Prepare workspace /environment for assembly	 The trainee must be able to: Check space availability Arrange racks for the equipment Place components based on functionality Ensure safety measures Ensure availability of consumables Ensure backup power source 	 Explain and demonstrate various space requirement for various assemblies Explain types of racks used for assembly. Demonstrate Procedure to arrange racks for assembly. Demonstrate arrangement of component as per assembly procedure Explain and demonstrate health and safety procedure (for equipment as well as personnel safety) Explain Difference Between tools and consumables Demonstrate Procedure for selecting the consumables. demonstrate procedure for cross checking of the consumable with standard list. Explain various power sources and its backup 	As Unit-1

usage. demonstrate procedure for using of backup power source. 	
Practical: prepare a workspace for given robotic assembly	

Example And Illustration









Prepare workspace /environment for assembly

https://www.youtube.com/watch?v=rDvggSDj4Sk





Module: 0714001058 Do component testing for robotics

Objective of the Module: This module deals with preparation of testing work bench, execute component testing for robotics and checking calibration status of the work bench. The learner will be able to perform component testing using the work bench and prepare a calibration report of test work bench after completing this competency level.

Duration:	Total hou	irs	40	Theory:	10	F	Practical	30
Learning Unit	Lea	rning C	outcomes	Learning Elemer	nts		Materia Equipr Requir	als (Tools & nent) red
LU1. Prepare test work bench	ng The trainee Identify compone Identify according standard Follow prepare t	must b work nts testing g to instruct est ben	e able to: bench criteria given tions to ch	 Explain Basic testing co Demonstrate Basic test Explain Testing Types Explain Hierarchical we details Demonstrate Develop C Practice: Collect all workbench testing as per given tas 	oncepts ting concepts workbench con Criteria for testir component de k.	nponent ng tails for	 Testing Wo Testing Corrobot Electrical to Mechanica Computers Stationary 	ork Bench omponents of ool kit I tool kit
LU2. Identify SOPs for component testing	 Identify requires te Identify procedure List SOF testing crit 	compon esting relevan es Ps acc teria	ents that t testing ording to	 Develop testing chiena Describe SOPs for identicating Demonstrate the testing p Practical perform testing of the give 	ntification of con procedure as per	SOP.		

LU3. Execute component test	 Follow SOPs to perform component tests Identify and log different performance parameters Ensure safety parameters while component testing Collect and compile test results Validate test results 	 Describe Execution order for component test Describe performance and safety parameters of individual components Demonstrate performance and safety parameters of individual components Perform Validation of test result and generate report as per results. Practical: Validate component testing Write Performance and safety parameters of component testing of given task Collect and compile test results 	As Unit-1
LU4. Report testing results	 The trainee must be able to: Identify relevant templates for report writing Prepare report on 	 Explain report writing and its techniques. Explain Report Writing on performance parameters and component faults Demonstrate Report Writing on performance parameters and component faults Describe component fault specific solution Demonstrate fault rectification. 	As Unit-1

•	 performance parameters Prepare report on component faults Report recommended solutions 	 Practical: Write Report on Performance parameters and write possible solutions 	
LU5. Verify Calibration status of testing equipment • • • • • • • • • • • • • • • • • • •	 The Trainee must be able to: Identify absolute instrument for calibration Identify Calibration parameters Perform calibration test according to instructions Compare calibration status with the instruction's manual Report calibration status of the testing equipment 	 Explain calibration testing Demonstrate calibration testing Explain verification of calibration testing Demonstrate verification of calibration testing Describe the calibration parameters Demonstrate how to perform calibration test according to instructions and compare calibration status with the instruction manual Practical: Perform calibration test according to instructions and compare calibration manual and generate the test report. 	As Unit-1

Exampel And Illustration



RPA Tools Uippath blueprism Automation Anywhere Buu can practice the RPA technology	Execute component test https://www.youtube.com/watch?v=kVtgA_PQ5R4
UI Path How to read excel data By Vivek	Report testing results https://www.youtube.com/watch?v=sTGcpeDJWMQ





Building a Testbed for FTC Robot Components

https://www.youtube.com/watch?v=IzugeZjWK-I

Module: 0714001059 Un Deploy robot at workplace

Objective of the Module: This Competency Standard is developed to train how to halt operation and uninstall robot at workplace for undeployment. After completing this standard, the trainee will be able to halt the operation, uninstall and undeploy the robot at workplace and efficiently transport it to the proper storage place.

Duration:	Total hours	40	Theory:	7	Prac	ctical	33
Learning Unit	Learnin	g Outcomes	Learning Elen	nents		Mater Equip Requ	ials (Tools & oment) ired
LU1. Halt operation of robot	 The Trainee must Identify proshutting down Follow steps standard oper Ensure safe during the prosent 	est be able to: cocedure for of robot. s provided in rating manual. ety standards cedure.	 Describe different down of robot. Describe different s followed. Demonstrate safety Demonstrate proce the robot. Practical: Given a robot fu platform, execute s 	procedures for standards that procedures. dures for shut rom a specif shutdown opera	r shutting should be ting down ic robotic ation while	ElectroMechaRobotiTransp	onic tool kit nical tool kit c Platform portation means

		ensuring that safety standards are followed.	
LU2. Prepare environment for undeployment	The Trainee must be able to:	• Describe the tools and equipment generally used for un-deployment	As Unit-1
	Identify tools and equipment required for unemployment	• Describe process for prepare the workplace for undeployment	
	Arrange tools and equipment required	Demonstrate the usage of tools and equipment generally used for unemployment	
	Ensure suitability of workplace for unemployment	 Practical: Given a robot from a specific robotic platform, identify the required tools and equipment. Also prepare the workplace for unemployment 	
LU3. Uninstall robot	 The trainee must be able to: Identify uninstallation procedure for robot from installation manual. Follow standard procedure to 	 Describe installation manual Describe standard procedure for uninstalling a robot Describe safety procedures for uninstalling robots Demonstrate uninstallation of robot 	As Unit-1
	 uninstall the robot Ensure safety of robotic components while uninstalling 	 Practical: Given a robot from a specific robotic platform, perform uninstallation according to standard procedure 	
LU4. Prepare components for transportation and storage (packing)	 The trainee must be able to: Identify packaging requirement of components Ensure proper packaging of components 	 Describe materials and methods for packaging Describe transportation procedure Describe storage procedures Demonstrate proper packaging of robot component Practical: Given a robot component, perform proper 	As Unit-1
	Arrange components for transportation and storage.	packaging of the component	
LU5. Transport and store components	The trainee must be able to:	 Describe various modes of transportation for robotic components Describe standard procedures for loading and unloading of components 	As Unit-1

• Identify mode of	Describe various storage procedures for
transportation.	components
• Ensure safe loading /unloading of the robotic	Demonstrate transportation of robotic component
components	Practical:
• Ensure appropriate storage environment for components	 Given a robotic component, transport it to storage area for storage

Example and Illustration





Mahindra Logistics Warehousing Image: Marehousing Image: Marehousing <th>Prepare components for transportation and storage (packing) https://www.youtube.com/watch?v=I4naUx5OAjU</th>	Prepare components for transportation and storage (packing) https://www.youtube.com/watch?v=I4naUx5OAjU
	Inside Axis 4,5 and 6 on a KUKA Robotic Arm https://www.youtube.com/watch?v=EfmjhfN8D-Q

	Fixing a KUKA KR-350/1 Robotic Arm: Part 1
	https://www.youtube.com/watch?v=6YiPrytt_Ss
1. Know your power tool—Read the owner's manual carefully. Learn its application and	Halt operation of robot:
limitations as well as the specific potential hazards peculiar to this tool.	
2. Ground all tools—If a tool is equipped with a three-prong plug, it should be plugged	
into a three-hole receptacle. If an adapter is used to accommodate a two-prong receptacle,	
the adapter wire must be attached to a KNOWN GROUND. Never remove the third	
prong.	
3. Keep guards in place—and in working order.	
4. Remove adjusting keys and wrenches—Form a habit of checking to see that keys	
and adjusting wrenches are removed from the tool before turning on any machine.	
5. Keep work area clear—Cluttered work areas and benches invite	

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accidents.

6. Avoid a dangerous work environment—Do not use power tools in damp or wet

locations. Keep your work area well illuminated.

7. Keep children away—All visitors should be kept a safe distance from the work area.

8. Make your workshop "kid-proof" —with padlocks, master switches or by removing

starter keys.

9. Do not force a tool—Do not force a tool or attachment to do a job for which it was not

designed. Use the proper tool for the job.

10. Wear proper apparel—Avoid loose clothing, neckties, gloves or jewelry that could

become caught in moving parts. Wear protective headgear to keep long hairstyles away

from moving parts.

11. Use safety glasses—Also use a face or dust mask if a cutting operation is dusty.

12. Secure the work—Use clamps or a vise to hold work when practicable. It is safer

than using your hand and frees both hands to operate the tool.

13. Do not overreach—Keep your proper footing and balance at all times.

14. Maintain tools in top condition—Keep tools sharp and clean for best and safest

performance. Follow instructions for lubrication and changing

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accesso	1103.

15. Disconnect tools—Unplug tools before servicing and when changing accessories

such as blades, bits or cutters.

16. Avoid accidental starting—Make sure the switch is "OFF" before plugging in a

power cord.

17. Use only recommended accessories—Consult the owner's manual. Use of improper

accessories may be hazardous.

18. Turn the spindle by hand BEFORE switching on the motor—This ensures that

the workpiece or chuck jaws will not hit the lathe bed, saddle or crosslide, and also

ensures that they clear the cutting tool.

[8:59 PM, 11/26/2019] Ibrahim: 19. Check that all holding, locking and driving devices are tightened—At the same

time, be careful not to over tighten these

[8:59 PM, 11/26/2019] Mughal: ok

[8:59 PM, 11/26/2019] Ibrahim: 20. Don't use your lathe for grinding— The fine dust that results from the grinding

operation is extremely hard on bearings and other moving parts of your tool. For the same

reason, if the lathe or any other precision tool is kept near an operating grinder, it should

be kept covered when not in use.

21. Don't let long, thin stock protrude from the back of the spindle-Long,

thin stock

that is unsupported and turned at high RPM can suddenly bend and whip around.

22. Wear your safety glasses—Foresight is better than NO SIGHT! The operation of

any power tool can result in foreign objects being thrown into the eyes, which can result

in severe eye damage. Always wear safety glasses or eye shields before commencing

power tool operation. We recommend a Wide Vision Safety Mask for use over spectacles

or standard safety glasses.

23. Checking/changing computer power supply voltage settings— Sherline attempts to

ship each CNC computer set to the proper voltage for the customer's country. Customers

outside the USA should check this setting to confirm it is correct before plugging in the

computer for the first time. If you need to change the voltage setting, there are two

switches. You must change both the 115V/230V power switch on the back of the

computer and the switch on the side of the driver board power supply inside the computer

case. For proper procedure, see Part I, System Components and Connections further on in

these instructions.

24. Static electricity can damage your computer—If the case must be

opened, be sure
you are properly grounded before touching any components inside your computer. A
spark of static electricity can damage delicate circuits in some components in your
computer. Either wear an approved static electricity grounding strap around your wrist or
touch the case of the computer with one hand before touching any components with your
other hand.
25. Be sure you know what will happen BEFORE pushing the [START] button—
Run your program in [BACKPLOT] mode before running the actual part to make sure it
will run the path your are expecting. Make sure your machine is in the proper home
position before starting the operation.

Module: 0714001060 De-commission robot at workplace

Objective of the Module: This Competency Standard identifies the competencies, for decommissioning and/or removal of equipment, is to ensure all equipment decommissioning/ removal and support systems decommissioning/removal are executed in a manner consistent with applicable codes, regulations and sound engineering practices. After passing this competency student will be able to ensure that equipment and support systems are decommissioned and removed in a manner that will allow lowest possible risk to employees, the facility, operations or maintenance activities. This competency standard deals with preparation of testing work bench, execute component testing for robotics and checking calibration status of the work bench. The learner will be able to perform component testing using the work bench and prepare a calibration report of test work bench after completing this competency level.

Duration:	Total hours	40 Hrs	Theory:	4 Hrs		Practical	36 Hrs
Learning Unit	Learning	Outcomes	Learning Ele	ements		Materials (Tools & Equipment) Required	
LU1. Prepar environment fo disassembling LU2. Disassembl undeployed robot	 The trainee must be Identify requirements Identify requirements Perform prechecks such health and safe Select approdisassembling The trainee must be Identify order of Identify order of Detach connection Follow the state procedure for or or obot 	e able to disassembling decommissioning as Environment, ety (EHS). priate tools for of robot. e able to disassembling ons effectively indard operating disassembling of	 Describe disassemb Describe checks that to decommissioning Describe tools to disassembly Demonstrate proceed disassembly Practical: Given a roboon disassembled, select tools for Describe how to disassembly Describe how to disassembly Describe different robotic unit Demonstrate how to disassembly Describe standard p the robot Demonstrate disassemble 	 Describe disassembling requirements Describe checks that should be performed prior to decommissioning Describe tools that can be used for disassembly Demonstrate process of tools selection for disassembly Practical: Given a robotic unit that needs to be disassembled, perform all checks and select tools for disassembly. Describe how to determine the order of disassembly Describe different types of connections in a robotic unit Demonstrate how to detach connections Describe standard procedure for disassembling the robot 			le of disposable, able and ble components anical Tool kit electronics kit
			PracticalGiven a robotic unit	that required disas	sembly		
LU3. Classify reusabl and repairabl components	e The trainee must b	e able to	 Describe procedu reusability of compo Describe procedu 	re for determin onent re for determin	ing the ing the		
	Identify reusabl components.	e and repairable	Demonstrate identification of reusable/repairable components Describe sorting techniques for components				
	• Sort reusable components.	and repairable	 Demonstrate sorting Describe labelling p 	g of components rocedure for compo	onents		

		Label reusable and repairable components.	 Demonstrate labelling of components Practical Given a number of components from a robotic unit, perform the following tasks: 	
			 Identify reusable components Identify repairable components Sort components according to reusable and 	
			repairableLabel components	
LU4. discarded	Dispose	The trainee must be able to:	Describe procedure for final testing of a component's reusability/repairability.	
components		Ensure that the component is not usable or repairable.	 Describe EHS procedures for disposing robotic components Describe procedure for disposal of components 	
		 Identify EHS procedure for dispose of discarded components 	Demonstrate disposal process for discarded components Demonstrate disposal process for discarded components	
		 Ensure proper disposal of discarded components 	 Given a number of discarded robotic components, perform final checks and dispose of the components properly following EHS guidelines 	

Chuck Installation Guide	Prepare environment for disassembling https://www.youtube.com/watch?v=F8X-Z6Sti1A
	Disassemble undeployed robot For disassembling a deployed robot. https://www.youtube.com/watch?v=1E017zUYMvw

Robotic Medical Syringe Assembly System with Six FANUC LR Mate Robots Courtesy of Farason Corporation	Robotic Medical Syringe Assembly System – Farason Corporation https://youtu.be/ykhYckjCfiU
Classify reusable and repairable components	Classify reusable and repairable components
Its example is as follows:	
AIRLINE MAINTENANCE	
Maintenance programs are evolved and developed for each new type of aircraft based on previous experience with similar materials, engines, components, or structures. New materials or structures, for which experience is limited, are observed more frequently until a basic level of confidence is established. Time extensions to inspection intervals are based on observations made during routine service checks. A typical airline maintenance and service plan is outlined in table 7-1. The objectives of an effective maintenance program are as follows (Edwards, 1994):	
Ensure, through maintenance activity, that the inherent safety and reliability imparted to an aircraft by its design are sustained.	
Provide opportunities to restore levels of safety and reliability when	

deterioration occurs.

Obtain information for design modification when inherent reliability is not adequate.

Accomplish the above at the lowest possible cost.

Structural Maintenance

Any new aircraft program is based on assessing structural design information, fatigue and damage tolerance evaluations, service experience with similar aircraft structures, and pertinent test results. Generally, the maintenance task evaluates sources of structural deterioration including accidental damage, environmental deterioration, and fatigue damage; susceptibility of the structure to each source of deterioration; the consequences of structural deterioration to continuing airworthiness including effect on aircraft (e.g., loss of function and reduction of residual strength, multiple-site or multiple-element fatigue damage, the effect on aircraft flight or response characteristics caused by the interaction of structural damage or failure with systems or power plant items, or in-flight loss of structural items); and the applicability and effectiveness of various methods of detecting structural deterioration, taking into account inspection thresholds and repeat intervals.

Component Maintenance

The application of new materials will not cause undue maintenance difficulties or hardship for the airlines provided the aircraft designer is familiar with component experience. Airline experience indicates that hardware items wear out, but statistical old-age wear-out in complex mechanical, electrical, and avionic components is not a dominant pattern of failure. In fact, over 90 percent of generic part types show either random distribution of failure or gradually increasing probability of failure with age (Edwards, 1994).

The reliability of a part or component of aircraft hardware is only as

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	good as its inherent design (supported by adequate maintenance) allows it to be. Hence, it is generally accepted that (1) good maintenance allows parts to reach their potential reliability; (2) overmaintaining does not improve reliability, but does waste money; and (3) undermaintaining can degrade reliability. In general, fundamental design changes are required to correct inherent component reliability problems.	
	There are three approaches to preventative maintenance that have proven to be effective. The first method, hard time, involves removing a unit from service when it reaches a pre-ordained parameter value. The second method, functional check or inspection, involves monitoring a characteristic dimension or usage/operating parameter of a piece of hardware to determine if it is still suitable for continued operation, or if it should be removed to prevent an in-service failure. The third method, functional verification, requires performing an operational check of hardware function(s) to determine each function's availability if it is normally hidden from the scrutiny of the flight and operating crew.	
	There are many components for which measurement of deterioration, periodic removal for maintenance, and hidden function verification are not economically feasible or beneficial. Such parts require routine performance or reliability	

Dispose discarded components https://www.youtube.com/watch?v=2ckHP-U-mZQ
Simplifying Communication https://kebblog.com/automation-components-for-robotic-systems/

PCA2017 Show	https://youtu.be/VPRkd3a7BIA
JPCA 2017	
Tokyo Big Sight June 7-9, 2017	
©2017 Kawasaki Heavy Industries, Ltd.	
	Robotic Assembly System for Electrical Wire Harnesses - Clear Automation https://www.youtube.com/watch?v=IAgrrqTgWbQ&feature=you tu.be

Module: 0714001062 Perform functional testing of robotics

Objective of the Module: This module aims to provide the required knowledge and skill to perform functional testing of robotics unit. This includes the ability to identify and execute testing procedures, as well as to examine interfaces and equipment. Upon completion of this module the learner will be able to generate comprehensive test reports.

Duration:	Total hours	60	Theory:	20	Practical	40

Learning Unit	Learning Outcomes	Learning Elements	Materials (Tools & Equipment) Required
LU1. Identify desired functionality for testing	 The trainee must be able to: List all functions of robotic unit Isolate functions that require testing Prioritize functions for testing Organize related functions into groups Identify and create testing procedures required to test functionality 	 Describe about functional testing Describe all the basic functionalities of robotic Unit. Demonstrate all the basic functionalities of robotic Unit. Describe the procedure for functional testing. Demonstration of procedure for functional testing. Demonstrate prioritization of function testing 	 Multi-meter Oscilloscope Computer systems Professional Electronic toolkit Professional Mechanical toolkit RPM meter Temperature meter Torque meter Barometer Robotic system Controller

LU2. Execute relevant testing procedure	 Prepare robotic unit for testing Identify testing procedure to be executed Select testing equipment to be used during tests Indicate required results to be achieved Execute testing steps in order Compile results of all tests 	 Describe the testing procedure for execution Describe all the testing tools used during test Demonstrate all the testing tools used during test Describe all the steps of testing while execution. Demonstrate all the steps of testing while execution. 	As Unit-1
		 Practical Create Testing Procedure for given task Execute testing step by step in order to perform all the functionality. Compile Results of all the functionality testing 	
LU3. Examine detailed functionality of interfaces	 List all interfaces Identify interfaces which can be examined Ensure firmware gave proper instruction to the hardware Organize interface in order of examination Identify acceptable functionality of interface Utilize the specific interface Examine functioning of the specific interface Analyse examination results Compile examination results 	 Describe the functionality of interfaces Demonstrate how to examine the interface Describe acceptable and non-acceptable functionality of interface Explain Firmware Describe the functionality of firmware and related issues. Demonstrate how to examine functioning of the specific interface Describe the analysis of results 	
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		 Practice: Examine function of interface and analyze examination results. 	

LU4. Examine detailed functionality of equipment	 The trainee must be able to: List all equipment who's functionality requires examination List functionality of equipment's to be examined Identify tools required for examination Arrange tools required for examination Identify acceptable functionality of equipment 	 Describe how to examine equipment and their functionality Describe tools and arrange tools for examination Describe acceptable and non- acceptable functionality of equipment Demonstrate acceptable and non- acceptable functionality of equipment Describe the analysis of results Demonstrate equipment using specific tools 	
	 Examine equipment using specific tools Analyze examination results Compile examination results 	 Practical: Examine function of equipment and analyze examination results. 	
LU5. Generate test report	 List all tests for which report is required Identify result outcomes that are required to be reported Prepare optimal template for test report Compose test report based on template 	 Describe Identification of result outcomes. Describe template for test report Describe the composition of test report based on template Describe the quality of test report Demonstrate how to assure quality of test report 	

 Assure quality of test report Identify distribution of report 	 Practical List all tests for reports Prepare template for report and compose test report with quality assurance. 	
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Example and Illustration



Identify desired functionality for testing

https://www.youtube.com/watch?v=lftyD7hnOqs

Execute relevant testing procedure

https://www.youtube.com/watch?v=6oyPcdtv7gc



Examine detailed functionality of equipment

https://www.financewalk.com/industry-analysis/

Examine detailed functionality of equipment https://www.financewalk.com/industry

The following is just for an example to visit the web site, Trainer can provide best example and illustration rather then this at run time as per the task given to the trainee

How to Do Industry Analysis, Examples, Steps, Porter Model.....

- The Need for Industry Analysis
- How to do Industry Analysis?
- Review available reports
- Approach the correct industry
- Demand & supply scenario
- Competitive scenario
- Recent developments
- Focus on industry dynamicsEndnote



GTAC 2015: Robot Assisted Test Automation

https://www.youtube.com/watch?v=oQRrk7S9sUE&feature=youtu.be



Robotic PCB Loader-Functional Test

https://youtu.be/qQiZSBk_ruA

0:06 / 30:04



Symbio RATA (Robot Aided Test Automation) Demo https://youtu.be/n_915xMRGAo

Generate test report

https://www.youtube.com/watch?v=80wCEQ55uf0

Lot Size	Sample Size	Acceptance No.	Rejection No.
08	Max. 5	0	1
o 15	5	0	1
to 25	5	0	1
to 50	5	0	1
to 90	20	1	2
to 150	20	1	2
to 280	32	2	3
to 500	50	3	4
to 1200	80	5	6
01 to 3200	125	7	8
01 to 10000	200	10	11
001 to 35000	315	14	15
000 to 150000	500	21	22
0001 to 500000	500	21	22
001 and over	500	21	22

Module: 0714001063 Commission robot at workplace

Objective of the Module: This competency level deals with preparing environment, unboxing, commissioning and initial testing of the robotic system. The learner will be able to commission a robotic system under supervision after completing this competency level.

Duration:	1	otal hours	60 Hrs	Theory:	12 Hrs	Pra	actical	48 Hrs	
Learning Unit		Lear	Learning Outcomes Learning Elements				Materials (Tools & Equipment) Required		
LU1. Prepare enviro for commissioning o	onment f robot	 The trainee r Specify conditions of robot. Prepare s for commit Arrange to required commission 	nust be able to: environmenta for commissioning suitable environment ssioning of robot. ools and equipment for the oning of robot.	 Describe envira- commissioning of Demonstrate pro- commissioning of Describe tools commission of ro- Demonstrate a commissioning of Practical Given a robot fro- prepare the envirand equipment for 	onmental requirer of robot eparation of enviro f robot and equipment re obot arrangement of f robot om a specific roboti vironment and arra or commissioning of	nents for onment for equired for tools for c platform, ange tools f robot	 R EI M C P 	obotic system lectronic tool kit echanical tool kit omputers rinters	
LU2. Unbox robotic s	system	 The trainee r Identify insuboxing r Arrange training required f 	nust be able to: structions manual for of robotic system. ools and equipmen or unboxing robotic	 Describe various Describe various Describe various unboxing robotic Describe how instructions given Demonstrate usa Demonstrate unb Practical 	types of instruction s tools and equi system to comprehend a n in manual age of instructional n poxing of robotic sys	n manuals pment for and follow manual stem	As unit-1		

LU3. Comprehend	 system Follow instructions provided in manual for unboxing of robotic system The trainee must be able to: 	 Given a robotic system, perform proper unboxing by following given instruction manual Describe various types of commissioning and 	As unit-1
commissioning and operational instructions	 Identify commissioning and operational manuals. Follow commissioning and operational instructions from manual Assist supervisor in 	 operational manuals Describe how to comprehend and follow instructions given in manuals Demonstrate usage of instructional manual Demonstrate unboxing of robotic system Practical Given a robotic system, perform proper unboxing by following given instruction manual 	
	 Assist supervisor in commissioning steps provided in manual. 		
LU4. Perform basic assembly	 The trainee must be able to: Identify required basic assembly Prioritize basic assembly based on requirements Follow instruction manual to basic basic	 Describe basic assembly required for commissioning of robot Describe procedure for determining the order of assembly Describe how to comprehend assembly instructions from manual Demonstrate basic assembly of robot Practical Given a robot that requires basic assembly, perform the said assembly as per instructions 	
1115 Perform initial testing	perform basic assembly	given in manual	
of commissioned robot	 Perform initial tests of commissioned robot. Follow steps for initial testing of robot 	 Describe different initial tests for robot Describe all steps required for perform initial tests Describe reporting formats for reporting test repute 	
	 Prepare initial testing report 	 Demonstrate initial testing of robot Demonstrate test reporting Practical 	

Given a newly commissioned robot,	
perform initial testing as per requirements	
and generate a test report	

Example and Illustration









Perform initial testing of commissioned robot

https://www.youtube.com/watch?v=8btqQDsM1Tk

Module: 0714001064 Deploy robot at workplace

Objective of the Module: This competency level is about preparing the deployment site along with transportation, installation and initial testing of the robotic system. The learner will be able to transport and deploy the robotic system at suitable site.

Duration:	Total hours	60 Hi	rs	Theory:	12 Hrs		Practical		48 Hrs
Learning Unit	Learning Out	comes		Learning Elemen	its		Mat Equ	terials (To uipment) Re	ols & quired
LU1. Prepare environment for deployment of robot	 The trainee must be all Specify er parameters for de robot. Identify suitable envideployment of robot Prepare suitable for deployment of ro 	ble to: nvironmental ployment of ironment for environment bot.	 De de en De en De de Pract Giv pa the 	escribe environmental ployment of robot escribe procedure for vironment for deploym emonstrate how to pre ployment of robot tical ven a robot, detern rameters required for e environment for deplo	parameters requi determining suitat ent epare the environm mine the environ deployment and p oyment	red for bility of ment for mental brepare	 Rot Ele Mea Cor Prir Tra 	ootic system ctronic tool k chanical tool mputers nters nsportation i	cit kit means
LU2. Transport robot and relevant system to deployment site	 The trainee must be all Identify transportation the robotic system. Arrange transportation robot to the deploym Ensure safe transportation to the deploym 	ole to: on means for tion of the nent site. portation of	 Dessuit Desde Desde Desde Desde Desde Construction Construct	escribe transportation stem escribe planning of tran emonstrate transportat ployment site escribe safety preca insportation tical ven a robotic system stem to the deployment	procedures for hsportation tion of robotic sys autions required m, transport the ht site safely	robotic stem to during robotic	As unit-1		

	the robotic system.		
CU3. Install robot at site	 The trainee must be able to: Identify installation manuals. Arrange tools and equipment required for the deployment of robot. Follow instructions provided in manuals to install the robot at site. 	 Describe various installation manuals Describe various tools and equipment available for deployment for robot Describe procedure for installing the robot at deployment site Demonstrate installation of robot at deployment site as per instructions given in manual Practical Given a robotic system, perform installation of the robot at the deployment site as per instructions 	As unit-1
LU4. Execute initial testing of deployed robot	 The trainee must be able to: Comprehend initial tests of deployed robot. Follow steps for initial testing of deployed robot. Prepare initial testing report. 	 Describe initial testing of robotic system after installation Describe how to prepare testing report Demonstrate testing of robotic system after installation Practical Given a newly installed robotic system, perform post installation initial tests and generate test report 	As unit-1

Examples and Ilustration



	Robots for the workplace
AP	
	https://www.youtube.com/watch?v=qp3dGUsyXS4
ternalia T	
AP	
▶ ▶ 🔌 0:05/6:14 🔤 🖬 🗖 🚺	
	Sharing a workplace with robot
	https://www.voutube.com/watch?v=AMWUUQ-1tMg
	https://www.youtube.com/watch?v=AMWUUQ-1tMg

Module: 0714001065 Monitor Operations of robot at workplace

Objective of the Module: This module covers the learning units required to monitor operation of robot at workplace. The trainee will be able to identify desired outcome of robot operation, identify errors, perform corrective measure, prepare operation report and maintain historic log..

Duration:	Total hours	40	Theory:	10	Practic	al	30
Learning Unit Learning Outcomes Learnin				Learning Elements			als (Tools & ment) red
LU1. Identify desired outcomes of robot operations	 The trainee must be List all robot ope Select robot o which outcomes identified List all possible specified robot o Recognize parameters t 	able to: ration peration for have to be outcomes of peration important o assess	 Explain all robot's op for particular outcome Outline all possib assessment criteria 	perations and its	selection • and its •	 Roboti Electro Mecha Compute Printer Transponsi 	c system onic tool kit nical tool kit uters s oortation

	outcomes of robot operation.Identify desired outcomes	Practical-1: Enlist all possible operation of robot with their possible outcomes. Practical-2 Enlist criteria for assessing an outcome of robot operation	means
LU2. Examine outcomes against established thresh hold	 The trainee must be able to: List established thresh holds for outcome Assess outcomes of the robotic operation Compare outcome against established thresh holds 	 Describe thresholds and their assessment criteria's Demonstrate any outcome of robotic operation against established threshold. Practial-1: Identify any particular threshold then compare it according to the established threshold. 	
LU3. Identify short comings in outcomes	 The trainee must be able to: Examine errors in outcomes Apply corrective measure to eliminate errors Prepare operation report 	 Explain different types of errors in outcome and their respective corrective measures Demonstrate types of errors in outcome and their respective corrective measures Practical-1: Analyze and prepare report on the outcome of any robot operation by identifying errors and eliminating them. 	

		•	
LU4.Maintain historic	 The trainee must be able to: Identify log parameter Prepare routine log Create sense of continuity and consistency while maintaining logs Keep the log factual and detailed 	 Explain the following: Log parameters Routine log preparation continuity and consistency in logs Details required in maintaining log Demonstrate report on existing Historical log which includes identification of log parameter etc. Practical-1: Prepare routine log report, add all required parameters and information. Make sure logs have sense of continuity, consistency and contain factual details.	

Examples and Illustrations

Why Robotics	Outcomes & Benefits of Robotic Joint Replacement Surgery with Dr. Charles Rutherford
	https://www.youtube.com/watch?v=F0kIfOzNVhY
 Total hip and knee replacements currently have a 90-95% success rate 	
 What about the other 10%? 	
Patient satisfaction 80-85%	
	Japan's robot revolution - BBC Click https://www.youtube.com/watch?v=zKhm89FWOy8



Module: 0714001066 Perform assembling of equipment / components

Objective of the Module: The objective of this exercise is to make a functional robot by performing assembly of equipment/ components. The trainee will be able to understand the robot architecture and will be able to assemble various types of robots.

Duration:		Total hours	40 Hrs	Theory:	8		Practical	32
Learning Unit Learning Outcomes		Outcomes	Learning Eleme	nts		Materia Equipr Requir	als (Tools & ment) red	
LU1. Comprehend as manual	sembly	 The trainee must b Acquire list manuals Select relevation man Read instruthoroughly Mark relevation man 	e able to: of assembly ant assembly/ uals ction manual nt steps for	 Define assembly man Explain purpose of as Describe how we assembly manuals. Explain how to carmanuals for assembling Practical: Select any mode available and assembling manuthe relevant steps report. 	uals. sembly manu can choose ollect all as ng a Robot. I of Robot w collect all uals and the for assembly	als. correct sembly which is of its n write in your	 Mechanica Electrical to Robotic too 	I tools kit ool kit ol kit
LU2. Prepare assembly	plan	 The trainee must b List the operation assembly Organize the assemble the training of traini	e able to: on procedure for ssembly plan	 Describe each op for assembly. Explain how to o assembly. Explain the purpo in assemble a Rot 	perational pro rganize any p se of each too pot.	ocedure blan for ol used	As Unit-1	

	 Make list of required items Identify necessary tools required for assembly Devise an alternate plan if necessary 	Practical: Make a list of operational procedures for assemble a robot and collect all tools required for assembling.	
LU3. Perform assembly as per SOP	 The trainee must be able to: Ensure safety standards Prepare a working environment for assembly List all steps as per SOP. Prioritize the assembly steps Follow the assembly steps. 	 Define health and safety standards. Use proper working gear during working. Describe working environment. Ensure use of proper lifting machinery for Robot handling. Define all SOP for assembling. Define all assembly steps. 	
		Practical: Make a report with pictures which shows all the steps of assembling a robot with safety measures.	

LU4. Verify assembly as per standards	 The trainee must be able to: List all assemblies performed Select assemblies that require verification Identify verification procedure for selected assembly Match the assembly with the drawing 	 Elaborate verification procedure. Describe the assembly which needs to be verified. Explain the drawing of each assembly. Describe procedure to inspect the joints coupling. Describe all power up connections. 	As unit-1
	 Inspect joint/links coupling of the robot Verify the wire connections Compare assembly with the manual Generate verification report 	Practical: Assemble the complete robot and make a report with pictures to elaborate all wiring connections, procedure of assembly verification and inspection of joint coupling.	

Example and Illustrations

	Comprehend assembly manual of robot
	https://www.youtube.com/watch?v=I1MOxx0Q1D0
(C) Cross	
	Electronics Assembly, Machine Tending & Material Handling -
Show	Kawasaki duAro robot
	https://www.youtube.com/watch?v=vPKku3a/biA
JPCA 2017	
Tokyo Big Sight	
June 7-9, 2017	
© 2017 Kawasaki Heavy Industries, Ltd. ♦ ▶ ₩ ₩ 0:01/3:31	



	How to assemble the 2WD Smart Robot Car Chassis Kit for Arduino
	https://www.youtube.com/watch?v=H78t6dnSoG0
How to Build	
an	
Arduino Robot by	
Thomas Messerschmidt	
	Fast Extreme Automatic Car Manufacturing Factory, Modern Mercedes Benz Assembly Technology
	https://www.youtube.com/watch?v=5pn8qAKL0V4
▶ N 🔌 0:13 / 13:39 🗰 🖬 🖬 🖬 🖬 🖬 🖬 🖬 🖬	



Module: 0714001072 Perform maintenance of robotics

Objective of the Module: This Competency Standard identifies the required skills and knowledge to adopt for maintenance of robotic systems. After completing this competency trainee will be able to develop maintenance schedule, perform maintenance, supervise and ensure maintenance as per standard procedures. Trainee will also be able to perform post maintenance test to ensure proper working.

Duration: Total hours 50 Theory: 10hrs Practical 40hrs	Duration:	Total hours 50	Theory:	10hrs	Practical	40hrs
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Learning Unit	Learning Outcomes	Learning Elements	Materials (Tools & Equipment) Required
LU1.Develop maintenance schedule	 The trainee must be able to: Identify equipment that require maintenance Determine frequency of maintenance required Prioritize required maintenance Create database on equipment to be inspected and maintained Draft maintenance plan 	 Describe the importance of maintenance schedules Describe preventive maintenance to reduce downtime Describe maintenance logs, failure histories or maintenance records Demonstrate maintenance schedule Demonstrate prioritizing critical equipment schedule for maintenance Demonstrate Maintenance planning 	 Mechanical tools kit Electrical tool kit Robotic tool kit Robotic Platform

		Practical	
		 Develop maintenance schedule 	
		 Develop record of equipment maintained and inspected 	
LU2. Perform maintenance as per procedure standards and guidelines	 The trainee must be able to: Identify tool and equipment required for maintenance Arrange tool and equipment required to perform maintenance at workplace Read instruction manuals thoroughly to perform maintenance Follow, stops, provided, in stopdard 	 Describe the list of tool/ equipment required for maintenance and their arrangement Describe instruction manuals for maintenance Describe key steps involved in maintenance procedure Demonstrate tool/ equipment required for maintenance Demonstrate instruction manuals for maintenance Demonstrate key steps involved in maintenance Demonstrate key steps involved in maintenance Perform key maintenance steps using instruction 	As Unit-1
	Follow steps provided in standard procedure and guideline	manuals and appropriate tools and equipment	
LU3. Supervise	The trainee must be able to:	Describe list of duties for staff skill set	As Unit-1
maintenance staff		 Describe the importance of individual and teamwork 	
	 Formulate list of duties as per staff skill set 	 Describe standard maintenance procedures and guidelines. 	
	 Assign duties to staff 	 Demonstrate list of duties for staff skill set 	
	 Ensure individual and teamwork. 	 Demonstrate individual and teamwork for maintenance 	
	• Ensure maintenance carried out as per standard procedure and guidelines.	 Demonstrate standard maintenance procedures and guidelines. 	
		Practical	
		 Given a group of students perform supervisory role and assign duties. 	
		 Given a group of students perform standard maintenance procedures and guidelines. 	
LU4. Ensure	The trainee must be able to:	• Describe tasks for maintenance schedule and their	As Unit-1

time		duration	
maintenance to avoid negative outcomes	Identify critical path in maintenance schedule	 Describe generating reminder to maintenance staff for timely execution of maintenance tasks. 	
	• Ensure timely reminder are issued to the maintenance staff.	• Describe key steps to implement complete maintenance in timely manner.	
	• Ensure timely execution of activity in critical path.	• Demonstrate timely maintenance check-ups and key steps to implement complete maintenance.	
	• Ensure strict adherence to overall		
	maintenance schedule.	Practical	
		 Implement timely maintenance check-ups and key steps to complete maintenance. 	
LU5. Perform	The trained must be able to:	Describe the list of most maintain and a toots	As Unit-1
component /		Describe the list of post maintenance tests	
functionality test after maintenance	Identify post maintenance test.	 Describe standard operating procedures for performing post maintenance tests 	
	 Follow instruction to perform post maintenance test as per standard operating procedure. Perform corrective measure to make sure smooth operation of system 	 Demonstrate post maintenance tests to ensure system is behaving as expected 	
		Practical	
		 Implement post maintenance functional testing against requirements/specifications 	
LU6. Generate	The trainee must be able to:	Describe the purpose of maintenance report	As Unit-1
report		 Describes steps for creating a maintenance report 	
	• Enlist results of functionality tests performed after maintenance	• Demonstrate maintenance report generation to review and manage information about equipment and its	
	Formulate maintenance report	maintenance.	
	• Propose any changes in maintenance		
	plan	Practical	

	Generate maintenance report to review and manage information about	
	Equipment and its maintenance.	

Example and Illustrations





How To Grease An Industrial Robot

https://www.youtube.com/watch?v=t1RJGHWIVwM



The use of robots have brought many benefits to manufacturers, but in order for them to continue seeing those benefits a robot equipment maintenance program must be implemented. The most common form of a robot maintenance program is preventive maintenance. Preventive maintenance is the planned maintenance of facilities and equipment, designed to eliminate unexpected breakdowns and increase the life span of robots. These programs are critical for the performance of a robot to remain reliable.

What is preventive maintenance?

Preventive maintenance involves expanding the life of robotic equipment through <u>painting</u>, lubrication, cleaning, adjusting, and minor part replacements. It uses testing, periodic inspections, and pre-planned maintenance activities in order to correct or prevent any problems that may arise. The main purpose is to keep breakdowns and decline to a

minimum.
Advantages of Robotic Maintenance Most robots breakdown as a result of wear and tear, but preventive maintenance prevents this from happening for several years.
With the prevention of breakdowns manufacturers' productivity and quality are increased.
Costs are reduced through preservation of assets; meaning that robotic equipment lasts longer eliminating the spending of money to replace it year after year.
It also has the potential to produce greater ROI. With an increased life span, robots prove to be well worth the investment for manufacturers.
<i>Implementing Preventive Maintenance</i> In order to have a successful preventive maintenance program it is important to execute a strict schedule with aggressive monitoring.
The program should focus on cleaning, lubrication, and fixing any problems found during inspections.
It is also critical to implement maintenance training among employees because warranties are limited. Having your own service personnel allows for quick repair time.
When to Implement Preventive Maintenance Plans: These are the top reasons for implementing a preventive maintenance program. If your company has or is

experiencing any of these then it may be time to start your own robotic maintenance program.
Increased automation
Production delays resulting in lost business
Decreased insurance inventories
Need for high quality products
Excessive consumption of energy
Disorganized working environment
Slow manufacturing time

Module: 0714001073 Perform trouble shooting

Objective of the Module: This competency standard deals with identification and rectification of the problem occurred in the robotic system. The learner will be able to identify and resolve the problem according to the troubleshooting manual. It also helps the learner to prepare a comprehensive diagnostic report of the troubleshooting.

	Duration:	Total hours 60		Theory:	12	Practical	48
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Learning Unit	Learning Outcomes	Learning Elements	Materials (Tools & Equipment) Required
LU1. Identify the problem	The trainee must be able to:	• Describe the steps to examine the robotic system.	Tool Kit (Electrical and

LU2. Gather more details related to problem	 Examine the robotic system. Enlist the identified problems. Classify the problems. Classify the problems. The trainee must be able to: Identify reasons for the specified problem. Observe the parameters and conditions at the time of problem occurred. 	 Describe the list of common problems of a robotics system and their categories Practical Examine the robotic system and identify problem and its category Describe the list of problems and causes. Describe variations in parameters robot condition, during anomaly Demonstrate report preparation to highlight problems in robotic system, variations in parameter and identified 	Mechanical) Robotic Platform Computers Printers Notepads As Unit-1
	Prepare a detailed report on the problem.	 Practical Implement detailed report to highlight problems in robotic system, variations in parameter and identified causes. 	As Unit-1
LU3. Identify possible solutions	The trainee must be able to:Identify the troubleshooting manual.	 Describe the usage of troubleshooting manual. Describe the corrective measures for troubleshooting using manual. 	As Unit-1
	 Specify the corrective measures from the troubleshooting manual. Arrange tools and equipment required to attempt fixing the problem. 	 Describe tools and equipment required to attempt fixing the problem. Demonstrate the usage of troubleshooting manual. Demonstrate the corrective measures for troubleshooting using manual and equipment required to attempt fixing the problem. Practical 	As Unit-1
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		 Implement troubleshooting using manual and equipment required to attempt fixing the problem. 	
LU4. Attempt a fix based on findings	 The trainee must be able to: Follow instructions from troubleshooting manual to resolve the problem. Gather more information and repeat if the problem is not resolved. Make a detailed report on rectification of the problem. 	 Explain instructions from troubleshooting manual. Describe the detailed report on rectification of the problem. Demonstrate trouble shooting using manual and repeat if the problem is not resolved. Demonstrate detailed report on rectification of the problem. 	As Unit-1
		Troubleshoot problems using manual and repeat if the problem is not	

LU5. Generate diagnostic report	 The trainee must be able to: Note the parameters and 	 resolved. Create a detailed report on rectification of the problem. Describe parameters and conditions that indicate cause of problem and their normal state after fixing the problem. Describe the report on the observations and rectification of the problem. 	As Unit-1
	 conditions after fixing the problem. Prepare a comprehensive report on the observations and rectification of the problem. Maintain error logs. 	 Describe error logs. Demonstrate identification of parameters and conditions that indicate cause of problem and their normal states after fixing the problem. Demonstrate report on the observations and rectification of the problem and error logs. 	
		 Practical Implement identification of parameters and conditions that indicate cause of problem. Implement report on the observations and rectification of the problem and error logs. 	

RobotWorx	Preventative Maintenance 101: Robot Cables https://www.youtube.com/watch?v=DHbxGr8cBfM
	Automated Manufacturing Robots https://www.youtube.com/watch?v=s-yne8xTNM0



57 Debet Diagnostic
https://www.youtube.com/watch?v=8fVTJtkn5J8
Error and Fault Recovery in Fanuc Robotic Controller
https://www.youtube.com/watch?v=uOYctsuNOyo

Module: 0714001074 Revise the configuration of robotics

Objective of the Module: This Competency Standard covers the required skills and knowledge for revising configuration of the robotic system according to the need of specified task. The trainee will be able to learn how to identify and reconfigure software and hardware modules of the robotic system as per desired task.

Duration:	Total hours	50 Hrs	Theory:	10 Hrs	Practical	40 Hrs
Learning Unit	Learning Learning Outcomes Unit		arning Elements			Materials (Tools & Equipment) Required
LU1. Verify detailed	The trained must be able t	Describe	e functionality tests			Robotic System

LU1. Verify detailed functionality of equipment	 The trainee must be able to: Identify functionality tests for checking robot Perform functionality test for robot Ensure proper functionality 	 Describe functionality tests Describe the procedure for conducting functionality tests Demonstrate functionality tests Practical Given a robotic equipment, perform functionality tests as per requirement to verify that ii is functioning properly 	Robotic System Mechanical Tool Kit Electronic Tool Kit Laptops
	of the equipment		
LU2. Verify detailed functionality of interface	The trainee must be able to:	 Describe various interfaces of robotic components Describe various functionality tests for testing the functionality of interfaces 	
	Identify interfacing modules	 Demonstrate functionality tests of interfaces Practical Given robotic components with various interfaces, perform 	

LU3. Identify task that require re- configuration of equipment	 for robot Perform functionality test Ensure proper functionality of the interface modules The trainee must be able to: Specify the task which will require re configuration. 	 functionality testing of those interfaces to ensure proper functionality Describe various configurations of robotic systems Demonstrate how to identify tasks that require reconfiguration Describe tools and equipment that can be used for reconfiguration Describe various robotic components that can be used for reconfiguration. 	As Unit-1
	 List required tool and equipment for reconfiguration. List down robotic components necessary for reconfiguration 	 Practical Given a robotic system that needs to be reconfigured for some other task, identify the components that require reconfigurations and provide a list of equipment, tools and robotic components that will be required 	
LU4. Ensure integration of reconfigured equipment	 The trainee must be able to: Arrange robotic components necessary for reconfiguration Identify standard procedure for integration Perform integration of reconfigured equipment 	 Describe robotics components that can be reconfigured Describe the standard procedure for reconfiguring robotic component Describe the procedure for performing integration Demonstrate integration of reconfigured components Practical Given a robotic system with reconfigure components, perform integration of the reconfigured components 	As Unit-1
LU5. Upgrade software modules	 The trainee must be able to: Identify software modules that require up gradation Backup existing software 	 Describe procedure for backup of software and configuration Describe procedure for upgradation of software modules Describe procedure for identify software modules that required upgradation Demonstrate backup of software and configuration Demonstrate upgradation of software modules Practical Given a robotic system, perform backup of the existing 	As Unit-1

	 and configuration. Perform up gradation of software modules according to the SOP. 	software and configuration. Identify modules that require upgradation and perform upgradation of those modules	
LU6. Ensure testing and smooth functionality of equipment	 The Trainee must be able to: Identify standard testing procedures. Perform functionality test of the reconfigured equipment Ensure proper functionality of the reconfigured equipment Maintain log of equipment reconfiguration 	 Describe standard testing procedures Describe standard procedure for maintaining log Demonstrate functionality testing of reconfigured component Demonstrate maintaining equipment log Practical Given a reconfigured robotic system, perform functionality testing of the reconfigured components and prepare reconfiguration log 	As unit-1

EPFL About E	ducation Research Innovation Schools Campus 50 years Q	Reconfigurable Robotics Lab
Reconfigurable Robotics Lab Our Lab Our Research Our Publications Spin-Offs	Reconfigurable Robotics Lab	https://www.epfl.ch/labs/rrl/
News & Press Open Positions Contact		





How to: Software and Firmware Update on a Universal Robot https://www.youtube.com/watch?v=1HFZ5vXjR0Q

Ensure testing and smooth functionality of equipment

Preventative Maintenance for Industrial Robots

Every robot needs preventative maintenance ensure top-level performance and consistency on the production line. When robots do not have regular preventative maintenance checks performed, it can cause parts and components to break down or malfunction, which can cause a slowdown or shutdown of your production. Industrial robots that are properly maintained can last for many years, even decades, before needing to be replaced. By keeping a regular preventative maintenance schedule, you are extending the life of your robot exponentially.

Different robotics companies recommend different amounts of time between preventative maintenance. For example, FANUC Robotics states that planned preventative maintenance for your industrial robot should be performed every 3,850 hours or 12 months, whichever comes first for your robot. However, KUKA Robotics recommends preventative maintenance after 10,000 hours for their robots. It is important to check the manual for your specific robot to see what time frame is best.

No matter what length of time your manual recommends, by scheduling maintenance in this way, you are able to prevent costly downtime that is unplanned due to mechanic issues. While planned maintenance may shut down production for a short time, it is nothing compared to the production time you may lose if your robot stops working.
So, what takes place during routine preventative maintenance checkups? Here are some recommended maintenance tips to schedule throughout the life of your robot:
Backing up the controller memory
Monitor robot in regular motion, inspecting robot, harness and cables
Inspection of brake operation
Check robot repeatability
Listen for excessive audible vibration and noise
Grease joints, according to specific robot manual (or analyze grease if already performed)
Visual inspection of teach pendant and controller cables
Check cable connections, cooling fans, power supplies, safety equipment, and other equipment for functionality
Test and replace RAM and APC batteries, if required
Clean vents and filters with compressed air
Grease bushing and balancer
Tighten external bolts
Replace batteries in controller and robot arm when necessary
If any further action is required and the robot needs repairs, the technician should report the issues so arrangement can be made to make the needed repairs.

Module: 0714001075 Execute up-gradation of robotics

Objective of the Module: This Competency Standard covers the required skills and knowledge for execution of up-gradation of robotic equipment. The trainee will be able to learn about identification process of equipment up-gradation, installation of software, hardware components and post operating tests.

	Duration:	Total hours	50	Theory:	8	Practical	32
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Learning Unit	Learning Outcomes	Learning Elements	Materials (Tools &
LU1. Identify current state of equipment for up- gradation	 The Trainee must be able to: Identify reason for up-gradation of equipment Identify tasks and related component that need up-gradation Ensure need to upgrade equipment 	 Describe the advancement in Robotics Instrumentation Summarize the production difference using advance instruments Explain rate of increase of production rate using upgraded equipment. 	 Equipment) Required Robotic system Mechanical tool kit Electrical tool Kit Personal Computers / Laptops Notebook
LU2. Recommend up- gradation of specific equipment	 The Trainee must be able to: List components of equipment need to be upgraded List the new upgraded equipment Prepare report on recommended equipment 	 Identify the upgrade able instruments and their substandard. Describe briefly the advance technology regarding the factory plant. Illustrate the extended features of recommended instruments. 	As unit-1
LU3. Install / replace software modules	 The Trainee must be able to: Identify software module that needs replacement Follow standard procedure for up-gradation of software modules Report software modules upgraded 	 Outline out-dated features of software module. Explain step by step procedure of software update. Describe how to prepare report of software up gradation. 	As unit-1

LU4. Install / replace physical components	 The Trainee must be able to: Identify physical component that need replacement Follow standard procedure for up-gradation of physical modules Report physical components upgraded Ensure proper packaging and storage of replaced modules 	 Outline out-dated key points of physical component. Explain step by step procedure of physical module up gradation. Illustrate how to prepare report for physical module up gradation. Interpret industrial storage system for warehouses. 	As unit-1
LU5. Perform post up- gradation test	 The Trainee must be able to: List post up-gradation tests Follow post up-gradation test as per standard operating procedure Evaluate and report post up-gradation tests results 	 Summarize post up gradation techniques for particular robot. Describe step by step procedure for up gradation. explain how to generate report for an up graded system. 	As unit-1
LU6. Ensure expected outcomes	 The Trainee must be able to: List expected outcome of up-gradation Compare expected and evaluated post up-gradation results Ensure corrective measures to achieve expected outcome 	 Explain the expected changes after up gradation. Determine gap analysis by a comparison between expected and actual result. Describe in detail the ways to achieve the goal. 	As unit-1

	Introduction and History of Robots
INTRODUCTION	This example shows the upgradation of robot with revaluation of robotics.
<list-item><list-item><list-item><list-item></list-item></list-item></list-item></list-item>	https://www.youtube.com/watch?v=62e8c6ErWE8
	Installing Our KUKA KR-350/1 Industrial Robot (Project Jeff) https://www.youtube.com/watch?v=dYzelD_6JjY

The Robot Revolution: The New Age of Manufacturing Moving Upstream https://youtu.be/HX6M4QunVmA

Module: 0714001076 Develop 3D simulations

Objective of the Module: The objective of this exercise is to have the knowledge and understanding of 3D simulations. This includes managing 3D modeling tools, building and simulating 3D models, generating coordinating systems for 3D models, and testing generated G-Codes.

	Duration:			Total h	nours	40 H	Irs	Theory:		8 Hrs	F	Practica	al	32 Hr	S
	Learning		Lea	rning C	outcomes		L	earning Elements				м	laterials	(Tools	&
	Unit					-		· · · · · · · · · · · · · · · · · · ·				E	quipment)	Required	,
LU1. mode	Manage Iling tools	3D	The Traine	e must k	be able to:	•	Descrit Demon	be various modelling	g tools modelling	tool based or	n •	3D Auto0	modeling CAD, Googl	tools le sketche	(e.g. s)
	-		List the a	available	e modelling tools		require	ments	- in deal			3D si	mulation to	ols (e.a. F	roteus
			The Traine	e must b	be able to:	•	modelli	ing tool compatibility	ain docu Y	imentation o		and c	other simula	ation softw	vare of
			Select	the	required/related	•	Demon Demon	nstrate how to upgra	ide model leshoot m	ling tools odelling tools		robot	s)		

	 modelling tools Keep an up to date documentation of modelling tools with respect to compatibility Upgrading and troubleshooting modelling tools 	 Practical Given a set of modelling tools, prepare documentation to manage the tools, perform upgradation of the tools, perform troubleshooting 	Laptop (for running software)
LU2. Build models in 3D environment	 The Trainee must be able to: List the available simulation modes. Select the required simulation mode. Interpret the given design specifications Formulate the procedure to design the model Design the model according to specifications Cross-check design specifications with the built model 	 Describe various simulation modes Demonstrate selection of simulation mode based on requirements Describe how to interpret design specification Describe the standard procedure for designing the model Demonstrate designing the model according to specification Demonstrate how to validate the model against the given specification. Practical Given a design specification, prepare a 3D model according to specification and cross-check the specification with the built model 	As unit-1
LU3. Simulate 3D models	 The Trainee must be able to: Prepare modelling tool for simulation. Run basic simulation according to specifications Generate basic G-codes Prepare feasibility report 	 Describe how to use simulation mode in modelling tool Demonstrate how to run simulation Describe basics of G-code Demonstrate how to generate G-codes Describe how to prepare a feasibility report Demonstrate preparation of feasibility report. Practical Given a 3D model, run simulation on the model and generate G-codes. Also prepare a feasibility report 	As unit-1

LU4. Convert / generate coordinating system for 3D model	 The Trainee must be able to: Generate system coordinates according to deployment requirements 	 Describe coordinate conversion process Demonstrate how to generate systems coordinates based on requirements Demonstrate how to translate generated coordinate to physical coordinates. 	As unit-1
	Translate generated coordinates to physical workplace	 Practical Given a 3D Model, generate system coordinates and then translate them to physical workspace 	
LU5. Test generated G-Code	The Trainee must be able to:	 Describe how to setup working environment Describe work piece requirements and selection process 	As unit-1
	• Set up working environment for sample testing	 Demonstrate how to process work piece using G- codes Demonstrate how to prepare performance report. 	
	Acquire sample work piece	Practical	
	Perform practical implementation of the generated G-code	• Given G-codes generated from a 3D model, implement the G-code on physical work piece and prepare performance report	
	 Prepare performance report 		

MathWorks	Designing Robot Manipulator Algorithms
MATLAB and Simulink Robotics Arena	https://youtu.be/5DnKot3mMSc
Jose Avendano Sebastian Castro	
	https://youtu.be/U-eO5zu2onA

	Simulate Process with Human, Machine and Robot
	https://youtu.be/gtARDPBnhNI
LAYOUT CONFIGURATION	
Simulate Process with Human, Machine and Robot	
VISUAL COMPONENTS	
▶ ▶1 ♥ 0:00 / 25:50	
	How to Create MATLAB GUI - robot arm simulation
	https://youtu.be/xF1KaINQwa8
	https://youtu.be/xF1KaINQwa8
	https://youtu.be/xF1KalNQwa8
(1) Creating New CIU	https://youtu.be/xF1KaINQwa8
(1) Creating New GUI	https://youtu.be/xF1KaINQwa8
(1) Creating New GUI	https://youtu.be/xF1KalNQwa8



Module: 0714001077 Assist engineers in design, configuration and application

Objective of the Module: This competency standard explains how to assist engineers in executing the design process, managing tools/equipment and perform equipment tests according to given plan. The learner will be able to understand the design process, management of tools and equipment and performing equipment tests according to manuals after completing this competency.

Duration:	Total hours	30	Tł	neory:	6		Practical		24	
· · · ·									<i></i>	-
Learning Unit	Learning	Learning Outcomes			Learning Elements			rials	(Tools	&
							Equi	pment)	Requirea	
CU1. Execute repe	etitive/	be able to:	•	 Describe th 	e types of engin	eering	 Tool 	Kits	(electrical	and
manual design process				drawing.			mech	anical)		
	Collect the definition of	esign process in: eer.	struction	 What are t of engineer 	he basic compo ing drawing?	onents	• Test	, bench		
	• Follow the ins	structions to exec	cute the	Why are important?	engineering dra	awings	Com	outers		
	design process	5.	•	How do y	ou read engin	eering	Printe	ers		
	Report proble	ms occurred du	ring the	drawing?			Tools	for sys	stem calibra	ation

	design process.		
CU2.Manage tools and equipment	Identify tools and equipment to be used.	What tools do you need to make a robot?	As Unit-1
	• Follow instructions to arrange and calibrate the tools and equipment.	How do you start making a robot?	
	• Ensure availability of tools and	Which software is used in robotics?	
	equipment for a specified job.	 What is instrument and instrumentation? 	
	• Gather the tools and equipment after completion of the job.	Why instrumentation is required?	
CU3. Execute test plan	Prepare the test environment.	 What is the purpose of testing an installation? 	As Unit-1
	Arrange test tools and equipment.	What is testing and inspection in destrict installation?	
	Follow instruction to perform test.	What is Robot testing?	
	• Report the results of the executed test.	• What tools do you need to make a robot?	



Topics For Today's Session	UiPath Automation Examples Top 5 Automation Examples in UiPath RPA UiPath Training Edureka
1 What is Automation? 2 What is UiPath? 3 Automation Examples in UiPath	https://youtu.be/-KAjgwWF0hY
Numpkab:34 / 45:25 RPA Training using UiPath www.edureka.co/robot @sce or or <thor< th=""> or</thor<>	
	Design Process -
	https://youtu.be/KpWrHVo972g
Engineering	
Design	
Process	
FIOLESS	

Question	1	is a drawing giving details about size tolerance, heat treatment, etc.	A	Exploded drawing
			В	Production drawing
			С	Assembly drawing
			D	Machine drawing
Question	2	Detailed drawing of each part of a machine is called	A	Part drawing
			В	assembly drawing
			С	patent drawing
			D	tabular drawing

Question	3	In which operation, motion of job is rotary and motion of cutting tool is forward translating?	A	turning
			В	planning
			С	milling
			D	all of the mentioned
Question	4	Which type of cutting tools have wide application on lathes?	A	multi point
			В	single point
			С	both single point and multi point
			D	none of the mentioned

Question	5	In how many groups, cutting tools can be divided?	Α	2
			В	3
			С	4
			D	None of the Above

Question	6	Which kind of resistance is experienced in upset butt welding?	A	Thermal resistance
			В	Magnetic resistance
			C	Electric resistance
			D	d) Air resistance
Question	7	Resistances can be measured with the help of a	A	Wattmeter
			В	voltmeter
			C	ammeter
			D	ohmmeter and resistance bridge

Question	8	The use of instruments is merely confined within laboratories as standardizing instruments.	A	absolute
			В	indicating
			С	recording
			D	integrating
Question	9	Which of the following have a low loading effect?	A	Electrical system
			В	Electronic system
			С	Both have equal effect
			D	None of the mentioned

Question	10	To increase the current sensitivity below 10 mV, electronic instrument uses	A	Oscillator
			В	Modulator
			С	Transducer
			D	Amplifiers
Question	11	What is the least count of a micrometer?	A	0.01 mm
			В	0.02 mm
			С	0.1 mm
			D	0.2 mm

Question	12	In physics, a common instrument to measure diameter of a circle is known as	A	rule
			В	measuring tape
			С	calipers
			D	inch tape
Question	13	Error due to eye vision is termed as	A	climax error
			В	sight error
			С	parallax error
			D	visional error

Question	14	Which of the following is incorrect for Vernier height gauge?	A	Surface plate is used as datum surface for measurements
			В	These gauges can be used for scribing purposes
			C	Removable clamps are used
			D	Both the surfaces of measuring jaw should be at 450 to the base
Question	15	What is the total error in micrometer?	A	Positive and negative deviation from the zero point
			В	Error in parallelism
			C	Deviation from measurement of a nominal dimension
			D	Maximum difference between ordinates of cumulative error

Question	16	A measuring tape can measure length more than a/an	A	meter
			В	inch but less than a foot
			С	foot but less than a meter
			D	centimeter
Question	17	Why these 4 elements (confidentiality, integrity, authenticity & availability) are considered fundamental?	A	They help understanding hacking better
			В	They are key elements to a security breach
			С	They help understands security and its components better
			D	They help to understand the cyber-crime better

Question	18	ensures the integrity and security of data that are passing over a	Α	Firewall
		network		
			В	Antivirus
			С	Pentesting Tools
			D	Network-security protocols
Question	19	SSL primarily focuses on	A	Integrity and authenticity
			В	Integrity and non-repudiation
			С	Authenticity and privacy
			D	Confidentiality and integrity

Question	20	Which of the following are forms of malicious attack?	A	Theft of information
			В	Modification of data
			C	Wiping of information
			D	All of the mentioned
Question	21	From the following, which is not a common file permission?	A	Write
			В	Execute
			C	Stop
			D	Read

Question	22	Which of the following is the least secure method of authentication?	A	Key card
			В	fingerprint
			С	retina pattern
			D	Password
Question	23	What is the name for information sent from robot sensors to robot controllers?	A	emperature
			В	b) pressure
			С	feedback
			D	d) signal

Question	24	What is the name for space inside which a robot unit operates?	A	environment
			В	spatial base
			С	work envelope
			D	exclusion zone
Question	25	Which of the following terms IS NOT one of the five basic parts of a robot?	A	peripheral tools
			В	end effectors
			С	controller
			D	drive
Question	26	The number of moveable joints in the base, the arm, and the end effectors of the robot determines	A	flexibility
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			В	payload capacity
			С	operational limits
			D	degrees of freedom
Question	27	For a robot unit to be considered a functional industrial robot, typically, how many degrees of freedom would the robot have?	A	three
			В	four
			С	six
			D	eight

Question	28	Which of the basic parts of a robot unit would include the computer circuitry that could be programmed to determine what the robot would do?	A	sensor
			В	controller
			С	arm
			D	end effector
Question	29	The collaborative robot arms are designed to mimic the range of motion of a	A	Network
			В	Machine arm
			С	Device
			D	Human arm

Question	30	Which of the following terms refers to the rotational motion of a robot arm?	A	swivel
			В	axle
			С	retrograde
			D	roll
Question	31	First step in validating a test is to	A	analyze the job
			В	choose the tests
			С	administer the tests
			D	Relate test scores

Question	32	A test's validity can be demonstrated in	A	Two ways
			В	Three ways
			С	Four ways
			D	Five ways
Question	33	The problem that threatens the success of a project but which has not yet happened is called as	A	Bug
			В	Error
			С	Risk
			D	Defect

Question	34	When should Regression Testing to be performed?	A	When the project manager says
			В	After the software has changed.
			C	Whenever software testing team get the time.
			D	None of the above.
Question	35	Which of the following are objective of software testing?	A	Determines that software product satisfy specified requirements
			В	Demonstrate that software products are fit for use
			C	Detect defects
			D	All the above

Question	36	Which of the following terms refers to the use of compressed gasses to drive (power) the robot device?	A	Photosensitive
			В	hydraulic
			С	piezoelectric
			D	pneumatic
Question	37	With regard to the physics of power systems used operate robots, which statement or statements are most correct?	A	hydraulics involves the compression of liquids
			В	hydraulics involves the compression of air
			С	pneumatics involves the compression of air
			D	chemical batteries produce AC power

Question	38	Which of the following IS NOT one of the advantages associated with a robotics implementation program?	A	Low costs for hardware and software
			В	Robots work continuously around the clock
			С	Quality of manufactured goods can be improved
			D	Reduced company cost for worker fringe benefits
Question	39	Under the OSH Act, employers are responsible for providing a	A	Safe workplace
			В	b) Land
			С	c) Insurance
			D	d) Estimation

Question	40	Which of the following places would be LEAST likely to include operational robots?	A	warehouse
			В	factory
			С	hospitals
			D	private homes
Question	41	What are the common security threats?	A	File Shredding
			В	File sharing and permission
			С	File corrupting
			D	File integrity

Question	42	Which of the following is a good practice?	A	Give full permission for remote transferring
			В	Grant read only permission
			С	Grant limited permission to specified account
			D	Give both read and write permission but not execute
Question	43	Which of the following is a strong password?	A	19thAugust88
			В	Delhi88
			С	P@assw0rd
			D	!augustdelhi

Question	44	If a robot can alter its own trajectory in response to external conditions, it is considered to be	A	intelligent
			В	mobile
			С	open loop
			D	non-servo
Question	45	refers to a different set of tasks ensures that the software that has been built is traceable to Customer Requirements.	A	Verification
			В	Requirement engineering
			С	Validation
			D	None of the above

Question	46	verifies that all elements mesh properly and overall system functions/performance is achieved.	A	Integration testing
			В	Validation testing
			С	Unit testing
			D	System Testing
Question	47	What do you verify in White Box Testing?	A	Testing of each statement, object and function on an individual basis.
			В	Expected output.
			С	The flow of specific inputs through the code.
			D	All of the above.

Question	48	Who performs the Acceptance Testing while running the application of robot?	A	Software Developer
			В	End users
			С	Testing team
			D	Systems engineers
Question	49	Before handing over the software to the client, which testing is to be done in- house?	A	Alpha
			В	Beta
			С	Gamma
			D	Theta

Question	50	Applications such as robotics, expert systems, pattern recolonization, artificial neutral networks etc are	A	engineering software
			В	artificial Intelligence software
			C	system software
			D	product line software

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